



# AUTONOMOUS- NAVIGATION-DEMO- WITH-FREIGHT

## VIDEO TRANSCRIPT

I'm Nick Akiona, and I'm a researcher at Accenture Labs. I work on our robotics initiative. Right here next to me is a robot by Fetch Robotics called Freight. This robot is capable of autonomous navigation through a variety of different environments. It's primarily made and suited for the logistics spaces, where it's going through and picking packages, and taking them back and forth. But its core functionality is the ability to navigate between two points in a space that it maps out, without the need for additional infrastructure.

So right now we're just going to do something really simple. We're going to have the robot go over, and bring Ana a bottle of water, and show that it's going to avoid an obstacle.

If it were to continue straight, it would run right into the table. But it's going to go around the table and deliver it without any need for intervention. I just have to go to the GUI and click a point, and you'll see the light turn on and it's going to start navigating. It's going to recognize that this table is here, see it as an obstacle, re-plan around it, and continue on its way.

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